Two Dimensional Problems in Elasticity

Advanced Mechanics of Solids ME202

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Outline

2-D problems in elasticity

Plane stress and plane strain problems

Stress compatibility equation

Airy's stress function and equation

Polynomial method of solution

Solution for bending of a cantilever with an end load

2-D problems in elasticity

- The 3X3 matrices of stress and strain at a point in 3D problems is simplified to 2X2 in 2D problems
- These problems are defined in a region over a plane.
- > 2D problems in elasticity can be classified in to
 - Plane stress
 - Plane Strain
 - Axi-symmetric

► The stress and strain tensors of 2D problems in x-y plane are $\sigma = \begin{bmatrix} \sigma_x & \tau_{xy} \\ \tau_{yx} & \sigma_y \end{bmatrix} \quad \text{and} \quad \epsilon = \begin{bmatrix} \epsilon_x & \frac{\gamma_{xy}}{2} \\ \frac{\gamma_{xy}}{2} & \epsilon_y \end{bmatrix}$ Rest of the terms in 3D Tensor are either zero or related to those present in the 2X2 matrices by Hook's law

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Plane Stress

- Plane stress is defined to be a state of stress in which normal stress σ_z, and shear stresses τ_{xz} and τ_{yz} directed perpendicular to x-y plane are assumed to be zero.
- Plane stress typically occurs in thin flat plates that are acted upon only by load forces that are parallel to them.

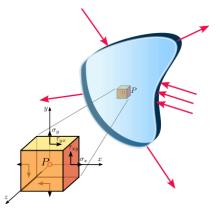


Figure: Plane stress

Plane Stress

Conditions for plane stress

 $\sigma_z = \tau_{xz} = \tau_{yz} = 0$, All other stress/strain components are independent of z-coordinate.

Generalized Hook's law

$$\epsilon_{x} = \frac{1}{E} (\sigma_{x} - \nu \sigma_{y})$$

$$\epsilon_{y} = \frac{1}{E} (\sigma_{y} - \nu \sigma_{x})$$

$$\epsilon_{z} = \frac{-\nu}{E} (\sigma_{x} + \sigma_{y}) \quad \text{In plane stress} \quad \epsilon_{z} \neq 0$$

$$\epsilon_{xy} = \frac{1}{2\mu} \tau_{xy} \quad \text{Or} \quad \tau_{xy} = G \gamma_{xy}$$

Plane Stress

Equilibrium conditions

$$\frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + \frac{\partial \tau_{xz}}{\partial z} + b_x = 0, \quad \text{Since} \quad \frac{\partial}{\partial z} = 0$$
$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_y}{\partial y} + \frac{\partial \tau_{yz}}{\partial z} + b_y = 0, \quad \text{Since} \quad \frac{\partial}{\partial z} = 0$$
$$\frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \sigma_z}{\partial z} + b_z = 0, \quad \text{Since} \quad \tau_{xz} = \tau_{yz} = b_z = 0, \quad \frac{\partial}{\partial z} = 0$$

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Plane Stress

Equilibrium conditions

$$\frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + b_x = 0$$
$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_y}{\partial y} + b_y = 0$$

Compatibility conditions

$$\frac{\partial^2 \epsilon_x}{\partial y^2} + \frac{\partial^2 \epsilon_y}{\partial x^2} = \frac{\partial^2 \gamma_{xy}}{\partial x \partial y}$$

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Plane Strain

- Plane strain is defined to be a state of strain in which the strain normal to the x-y plane, ε_z and shear strains γ_{xz} and γ_{yz} are assumed to be zero.
- This is possible, when the dimension of the solid is very large in z-direction compared to x and y directions, or when the displacement in a particular direction is

In plane strain, all the cross-sections parallel to the plane have the same stress pattern

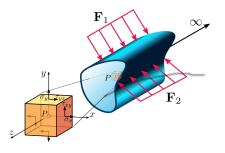


Figure: Plane strain

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Plane Strain

Conditions for plane strain

 $\epsilon_z = \gamma_{xz} = \gamma_{yz} = 0, u_z = 0$ All other stress/strain components are independent of z-coordinate.

Generalized Hook's law

$$\epsilon_{z} = \frac{1}{E} \left(\sigma_{z} - \nu \sigma_{x} - \nu \sigma_{y} \right) = 0 \implies \sigma_{z} = \nu (\sigma_{x} + \sigma_{y})$$

$$\epsilon_{x} = \frac{1}{E} \left(\sigma_{x} - \nu \sigma_{y} - \nu \sigma_{z} \right) = \frac{(1 - \nu^{2})}{E} \sigma_{x} - \frac{\nu (1 + \nu)}{E} \sigma_{y}$$

$$\epsilon_{y} = \frac{1}{E} \left(\sigma_{y} - \nu \sigma_{x} - \nu \sigma_{z} \right) = -\frac{\nu (1 + \nu)}{E} \sigma_{x} + \frac{(1 - \nu^{2})}{E} \sigma_{y}$$

$$\epsilon_{xy} = \frac{1}{2\mu} \tau_{xy} \quad \text{Or} \quad \tau_{xy} = G \gamma_{xy}$$

Plane Strain

Equilibrium conditions

$$\frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + b_x = 0$$
$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_y}{\partial y} + b_y = 0$$

Compatibility conditions

$$\frac{\partial^2 \epsilon_x}{\partial y^2} + \frac{\partial^2 \epsilon_y}{\partial x^2} = \frac{\partial^2 \gamma_{xy}}{\partial x \partial y}$$

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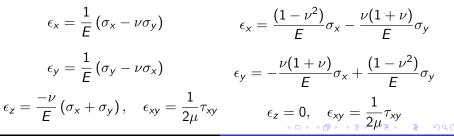
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Equivalance between Plane stress and Plane strain

- ► They both seek solutions for σ_x , σ_y , τ_{xy} and ϵ_x , ϵ_y , ϵ_{xy} as a function of x and y.
- They satisfy the same equilibrium and compatibility conditions.
- Only difference is in Generalized Hook's law.

Plane Stress

Plane Strain



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Stress compatibility equation

Five out of the six compatibility equations are exactly satisfied by the components of strain of 2D problems. The only one compatibility equation that requires agreement is

$$\frac{\partial^2 \epsilon_x}{\partial y^2} + \frac{\partial^2 \epsilon_y}{\partial x^2} = \frac{\partial^2 \gamma_{xy}}{\partial x \partial y}$$
Using $\gamma_{xy} = \frac{1}{G} \tau_{xy}$ and $\frac{1}{G} = \frac{2(1+\nu)}{E}$, we get
$$\frac{\partial^2 \epsilon_x}{\partial y^2} + \frac{\partial^2 \epsilon_y}{\partial x^2} = \frac{2(1+\nu)}{E} \frac{\partial^2 \tau_{xy}}{\partial x \partial y}$$
(3.1)

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Stress compatibility equation

We have the equilibrium equations in 2D

$$\frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + b_x = 0 \tag{3.2}$$

$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_y}{\partial y} + b_y = 0$$
(3.3)

Differentiating (3.2) with respect to x, and (3.3) with respect to y and rearranging,

$$\frac{\partial^2 \tau_{xy}}{\partial x \partial y} = -\frac{\partial^2 \sigma_x}{\partial x^2} - \frac{\partial b_x}{\partial x}$$
(3.4)
$$\frac{\partial^2 \tau}{\partial x^2} = -\frac{\partial^2 \sigma_x}{\partial x^2} - \frac{\partial b_x}{\partial x}$$

$$\frac{\partial^2 T_{xy}}{\partial x \partial y} = -\frac{\partial^2 \partial^2 y}{\partial y^2} - \frac{\partial^2 b_y}{\partial y}$$
(3.5)

Stress compatibility equation

Adding (3.4) and (3.5) \implies

$$2\frac{\partial^2 \tau_{xy}}{\partial x \partial y} = -\left(\frac{\partial^2 \sigma_x}{\partial x^2} + \frac{\partial^2 \sigma_y}{\partial y^2} + \frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y}\right)$$
(3.6)

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By putting (3.6) in (3.1) \Longrightarrow

$$\frac{\partial^2 \epsilon_x}{\partial y^2} + \frac{\partial^2 \epsilon_y}{\partial x^2} = -\frac{(1+\nu)}{E} \left(\frac{\partial^2 \sigma_x}{\partial x^2} + \frac{\partial^2 \sigma_y}{\partial y^2} + \frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y} \right) \quad (3.7)$$

Stress compatibility equation

Rearranging (3.7), we get

$$E\left(\frac{\partial^{2}\epsilon_{x}}{\partial y^{2}} + \frac{\partial^{2}\epsilon_{y}}{\partial x^{2}}\right) + (1+\nu)\left(\frac{\partial^{2}\sigma_{x}}{\partial x^{2}} + \frac{\partial^{2}\sigma_{y}}{\partial y^{2}}\right)$$
$$= -(1+\nu)\left(\frac{\partial b_{x}}{\partial x} + \frac{\partial b_{y}}{\partial y}\right) \quad (3.8)$$

Now, Hook's law can be applied to relate ϵ_x and ϵ_y in terms of σ_x and σ_y and final equation will be different for plane stress and plane strain problems as Hook's law expressions are different.

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Stress compatibility equation-Plane Stress

$$\epsilon_x = \frac{1}{E} (\sigma_x - \nu \sigma_y) \implies E \epsilon_x = (\sigma_x - \nu \sigma_y)$$
 (3.9)

$$\epsilon_y = \frac{1}{E} (\sigma_y - \nu \sigma_x) \implies E \epsilon_y = (\sigma_y - \nu \sigma_x)$$
 (3.10)

Differentiating (3.9) partially w.r.t x and (3.10) partially w.r.t y,

$$E \frac{\partial^2 \epsilon_x}{\partial y^2} = \frac{\partial^2 \sigma_x}{\partial y^2} - \nu \frac{\partial^2 \sigma_y}{\partial y^2}$$
(3.11)
$$E \frac{\partial^2 \epsilon_y}{\partial x^2} = \frac{\partial^2 \sigma_y}{\partial x^2} - \nu \frac{\partial^2 \sigma_x}{\partial x^2}$$
(3.12)

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Stress compatibility equation-Plane Stress

Adding (3.11) and (3.12) and rearranging,

$$E\left(\frac{\partial^{2}\epsilon_{x}}{\partial y^{2}} + \frac{\partial^{2}\epsilon_{y}}{\partial x^{2}}\right)$$
$$= \left(\frac{\partial^{2}\sigma_{x}}{\partial y^{2}} + \frac{\partial^{2}\sigma_{y}}{\partial x^{2}}\right) - \nu\left(\frac{\partial^{2}\sigma_{x}}{\partial x^{2}} + \frac{\partial^{2}\sigma_{y}}{\partial y^{2}}\right) \quad (3.13)$$

Substituting (3.13) in (3.8),

$$\begin{pmatrix} \frac{\partial^2 \sigma_x}{\partial y^2} + \frac{\partial^2 \sigma_y}{\partial x^2} \end{pmatrix} - \nu \left(\frac{\partial^2 \sigma_x}{\partial x^2} + \frac{\partial^2 \sigma_y}{\partial y^2} \right) + (1+\nu) \left(\frac{\partial^2 \sigma_x}{\partial x^2} + \frac{\partial^2 \sigma_y}{\partial y^2} \right)$$
$$= -(1+\nu) \left(\frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y} \right) \quad (3.14)$$

Stress compatibility equation-Plane Stress

$$\frac{\partial^2 \sigma_x}{\partial x^2} + \frac{\partial^2 \sigma_y}{\partial x^2} + \frac{\partial^2 \sigma_y}{\partial y^2} + \frac{\partial^2 \sigma_x}{\partial y^2} = -(1+\nu) \left(\frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y}\right) \quad (3.15)$$

$$\frac{\partial^2}{\partial x^2} \left(\sigma_x + \sigma_y \right) + \frac{\partial^2}{\partial y^2} \left(\sigma_x + \sigma_y \right) \\ = -(1+\nu) \left(\frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y} \right) \quad (3.16)$$

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right)(\sigma_x + \sigma_y) = -(1 + \nu)\left(\frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y}\right) \quad (3.17)$$

Stress compatibility equation-Plane Stress

$$\nabla^2 \left(\sigma_x + \sigma_y \right) = -(1+\nu) \left(\frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y} \right)$$
(3.18)

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Where $\nabla^2 = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right)$ is the Laplacian operator. Now, equations (3.2), (3.3) and the equation (3.18) make three equations for solving three unknowns σ_x , σ_y and τ_{xy} of a plane stress elasticity problem. Equation (3.18) is called **Stress** compatibility equation

Stress compatibility equation-Plane Strain

$$\epsilon_{x} = \frac{(1-\nu^{2})}{E}\sigma_{x} - \frac{\nu(1+\nu)}{E}\sigma_{y} \Longrightarrow$$
$$E\epsilon_{x} = (1+\nu)[(1-\nu)\sigma_{x} - \nu\sigma_{y}] \quad (3.19)$$

$$\epsilon_{y} = -\frac{\nu(1+\nu)}{E}\sigma_{x} + \frac{(1-\nu^{2})}{E}\sigma_{y} \Longrightarrow$$
$$E\epsilon_{y} = (1+\nu)[-\nu\sigma_{x} + (1-\nu)\sigma_{y}] \quad (3.20)$$

Differentiating (3.19) w.r.t y and (3.20) w.r.t x we get,

$$E\frac{\partial^{2}\epsilon_{x}}{\partial y^{2}} = (1+\nu)\left[(1-\nu)\frac{\partial^{2}\sigma_{x}}{\partial y^{2}} - \nu\frac{\partial^{2}\sigma_{y}}{\partial y^{2}}\right]$$
(3.21)

$$E\frac{\partial^{2}\epsilon_{y}}{\partial y^{2}} = (1+\nu)\left[(1-\nu)\frac{\partial^{2}\sigma_{y}}{\partial y^{2}} - \nu\frac{\partial^{2}\sigma_{y}}{\partial y^{2}}\right]$$
(3.21)
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Stress compatibility equation-Plane Strain

$$(3.21)+(3.22) \Longrightarrow$$

$$E\left(\frac{\partial^{2}\epsilon_{x}}{\partial y^{2}} + \frac{\partial^{2}\epsilon_{y}}{\partial x^{2}}\right) = (1+\nu)\left[(1-\nu)\frac{\partial^{2}\sigma_{x}}{\partial y^{2}} - \nu\frac{\partial^{2}\sigma_{y}}{\partial y^{2}} + (1-\nu)\frac{\partial^{2}\sigma_{y}}{\partial x^{2}} - \nu\frac{\partial^{2}\sigma_{x}}{\partial x^{2}}\right] \quad (3.23)$$

Substituting (3.23) in (3.8) we get,

$$(1+\nu)\left[(1-\nu)\frac{\partial^2\sigma_x}{\partial y^2} - \nu\frac{\partial^2\sigma_y}{\partial y^2} + (1-\nu)\frac{\partial^2\sigma_y}{\partial x^2} - \nu\frac{\partial^2\sigma_x}{\partial x^2}\right] + (1+\nu)\left(\frac{\partial^2\sigma_x}{\partial x^2} + \frac{\partial^2\sigma_y}{\partial y^2}\right) = -(1+\nu)\left(\frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y}\right) \quad (3.24)$$

Stress compatibility equation-Plane Strain

$$\begin{bmatrix} (1-\nu)\frac{\partial^2 \sigma_x}{\partial y^2} - \nu \frac{\partial^2 \sigma_y}{\partial y^2} + (1-\nu)\frac{\partial^2 \sigma_y}{\partial x^2} - \nu \frac{\partial^2 \sigma_x}{\partial x^2} \end{bmatrix} + \\ & \left(\frac{\partial^2 \sigma_x}{\partial x^2} + \frac{\partial^2 \sigma_y}{\partial y^2}\right) = -\left(\frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y}\right) \quad (3.25)$$

$$(1-\nu)\frac{\partial^2 \sigma_x}{\partial y^2} + (1-\nu)\frac{\partial^2 \sigma_y}{\partial y^2} + (1-\nu)\frac{\partial^2 \sigma_y}{\partial x^2} + (1-\nu)\frac{\partial^2 \sigma_x}{\partial x^2} = -\left(\frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y}\right) \quad (3.26)$$

 $\frac{\partial^2 \sigma_x}{\partial v^2} + \frac{\partial^2 \sigma_y}{\partial v^2} + \frac{\partial^2 \sigma_y}{\partial x^2} + \frac{\partial^2 \sigma_x}{\partial x^2} = \frac{-1}{(1 - v)} \left(\frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial v} \right) = (3.27)$ Advanced Mechanics of Solids ME202
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Stress compatibility equation-Plane Strain

$$\frac{\partial^2}{\partial x^2} \left(\sigma_x + \sigma_y \right) + \frac{\partial^2}{\partial y^2} \left(\sigma_x + \sigma_y \right) = \frac{-1}{(1-\nu)} \left(\frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y} \right) \quad (3.28)$$

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right)(\sigma_x + \sigma_y) = \frac{-1}{(1-\nu)}\left(\frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y}\right) \quad (3.29)$$

$$\nabla^{2} \left(\sigma_{x} + \sigma_{y} \right) = \frac{-1}{\left(1 - \nu \right)} \left(\frac{\partial b_{x}}{\partial x} + \frac{\partial b_{y}}{\partial y} \right)$$
(3.30)

This is Stress compatibility equation of plane strain problem.

Stress compatibility equation

$$\frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + b_x = 0$$
$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_y}{\partial y} + b_y = 0$$

Plane Stress

$$abla^2 \left(\sigma_x + \sigma_y
ight) = -(1+
u) \left(rac{\partial b_x}{\partial x} + rac{\partial b_y}{\partial y}
ight)$$

Plane Strain

$$\nabla^2 \left(\sigma_x + \sigma_y \right) = \frac{-1}{(1-\nu)} \left(\frac{\partial b_x}{\partial x} + \frac{\partial b_y}{\partial y} \right)$$

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Airy's stress function-Zero body forces

- ► Introduce a scalar function φ(x, y), and write different components of stress tensor as derivatives of φ
- ► Assume zero body force, b_x = b_y = 0 then the equilibrium conditions becomes

$$\frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} = 0, \quad \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_y}{\partial y} = 0$$

These can be automatically satisfied by defining

$$\sigma_x = \frac{\partial^2 \phi}{\partial y^2}, \quad \sigma_y = \frac{\partial^2 \phi}{\partial x^2}, \quad \tau_{xy} = -\frac{\partial^2 \phi}{\partial x \partial y}$$
(4.1)

The equilibrium conditions can be easily verified.

Airy's stress function-Zero body forces

 So only PDF we need to worry about is the compatibility condition.

Plane Stress:

$$abla^2\left(\sigma_x+\sigma_y
ight)=-(1+
u)\left(rac{\partial b_x}{\partial x}+rac{\partial b_y}{\partial y}
ight)$$

plane Strain

$$abla^2 \left(\sigma_x + \sigma_y
ight) = rac{-1}{\left(1 -
u
ight)} \left(rac{\partial b_x}{\partial x} + rac{\partial b_y}{\partial y}
ight)$$

 In case of Zero body forces both the above equations reduces to,

$$\nabla^2 \left(\sigma_x + \sigma_y \right) = 0 \tag{4.2}$$

Airy's stress function-Zero body forces

Substituting (4.1) in (4.2), we get

$$\nabla^2 \left(\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} \right) = 0$$

$$abla^2
abla^2 \phi = 0 \quad Or \quad
abla^4 \phi = 0$$
Where, $abla^4 = \left(\frac{\partial^4}{\partial x^4} + \frac{\partial^4}{\partial x^2 y^2} + \frac{\partial^4}{\partial y^4} \right)$

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Airy's stress function-in presence of body forces

 When the body force can be expressed as the derivatives of a potential

$$b_x = \frac{\partial V}{\partial x}, \quad b_y = \frac{\partial V}{\partial y}$$
 (4.3)

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Then Airy's stress function can be defined as

$$\sigma_{x} = \frac{\partial^{2}\phi}{\partial y^{2}} - V, \quad \sigma_{y} = \frac{\partial^{2}\phi}{\partial x^{2}} - V, \quad \tau_{xy} = -\frac{\partial^{2}\phi}{\partial x \partial y} \quad (4.4)$$

The equilibrium conditions can be easily verified.

Airy's stress function-in presence of body forces

> The equilibrium equations can be easily verified.

$$\frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + b_x = 0$$
$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_y}{\partial y} + b_y = 0$$

The compatibility conditions become,
 Plane stress
 Plane stain

$$\nabla^4 \phi = (1 - \nu) \nabla^2 V$$

$$\nabla^4 \phi = \left(\frac{1-2\nu}{1-\nu}\right) \nabla^2 V$$

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Polynomial of Degree One - An unstressed body

Consider
$$\phi(x, y) = a_1 x + b_1 y$$

$$\sigma_x = \frac{\partial^2 \phi}{\partial y^2} = 0, \quad \sigma_y = \frac{\partial^2 \phi}{\partial x^2} = 0, \quad \tau_{xy} = -\frac{\partial^2 \phi}{\partial x \partial y} = 0$$

The components of stress are zero. It represents an unstressed body.

Polynomial of Degree Two

Consider
$$\phi(x, y) = a_2 x^2 + b_2 x y + c_2 y^2$$

$$\sigma_x = \frac{\partial^2 \phi}{\partial y^2} = 2c_2, \quad \sigma_y = \frac{\partial^2 \phi}{\partial x^2} = 2a_2, \quad \tau_{xy} = -\frac{\partial^2 \phi}{\partial x \partial y} = 0$$

The components of stress are constant over the region(except shear). It represents a constant stress field.

If
$$a_2 = b_2 = 0$$
 and $c_2 = \frac{F}{2A}$, $\phi(x, y) = \frac{Fy^2}{2A}$,
 $\sigma_x = \frac{F}{A}$, $\sigma_y = 0$, $\tau_{xy} = 0$
This represents stress in an axial force member of area A applied
an axial force F

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Polynomial of Degree Three

Consider
$$\phi(x, y) = a_3 x^3 + b_3 x^2 y + c_3 x y^2 + d_3 y^3$$

$$\sigma_x = 2c_3x + 6d_3y, \quad \sigma_y = 6a_3x + 2b_3y, \quad \tau_{xy} = -2(b_3x + c_3y)$$

The components of stresses represents a linearly varying stress field. If $a_3 = b_3 = c_3 = 0$ and $d_3 = \frac{M}{6I}$, $\phi(x, y) = \frac{My^3}{6I}$, $\sigma_x = \frac{My}{I}$, $\sigma_y = 0$, $\tau_{xy} = 0$ This represents stresses in simple (pure) bending of a beam applied by a bending moment M.

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Polynomial of Degree Four

Consider
$$\phi(x, y) = a_4x^4 + b_4x^3y + c_4x^2y^2 + d_4xy^3 + e_4y^4$$

For this function to represent a stress function, it should satisfy

$$\nabla^4 \phi = \left(\frac{\partial^4 \phi}{\partial x^4} + \frac{\partial^4}{\partial \phi x^2 y^2} + \frac{\partial^4 \phi}{\partial y^4}\right) = 0$$

Substituting the partial derivatives,

$$24a_4 + 8c_4 + 24e_4 = 0 \therefore 3a_4 + 3e_4 + c_4 = 0$$

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Solution for bending of a cantilever with an end load

$$\phi(x,y) = axy + bxy^3$$

Clearly this function satisfies biharmonic equation of stress compatibility

$$\frac{\partial \phi}{\partial y} = ax + 3bxy^{2}$$
$$\sigma_{x} = \frac{\partial^{2} \phi}{\partial y^{2}} = 6bxy$$
$$\tau_{xy} = -\frac{\partial^{2} \phi}{\partial x \partial y} = -(a + 3by^{2})$$

Solution for bending of a cantilever with an end load

Boundary conditions of the problem are:

- 1. Stress free top and bottom layers, i.e. $\tau_{xy}(y = \pm h)$ Using this, we get $-(a + 3bh^2) = 0 \implies b = \frac{-a}{3h^2}$ $\tau_{xy} = -a\left(1 - \frac{y^2}{h^2}\right)$
- 2. Sum of total shear force on any cross section is equal to applied load P, i.e. $\int_{h}^{-h} \tau_{xy} t dy = P$

Solution for bending of a cantilever with an end load

$$\int_{-h}^{h} \tau_{xy} t dy = P$$

$$-\int_{-h}^{h} a \left(1 - \frac{y^2}{h^2}\right) t dy = -at \int_{-h}^{h} \left(1 - \frac{y^2}{h^2}\right) dy$$

$$= -at \left(y - \frac{y^3}{3h^2}\right)_{-h}^{h}$$

$$= -2at \left(h - \frac{h}{3}\right) = -\frac{4ath}{3} = P$$

$$\implies a = -\frac{3P}{4th}, \quad b = \frac{P}{4th^3}$$

Solution for bending of a cantilever with an end load

$$\phi(x, y) = \frac{P}{4th} \left[\frac{xy^3}{h^2} - 3xy \right]$$
$$\sigma_x = \frac{3P}{2th^3}xy$$
$$\sigma_y = 0$$
$$\tau_{xy} = \frac{3P}{4th^3}(h^2 - y^2)$$

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